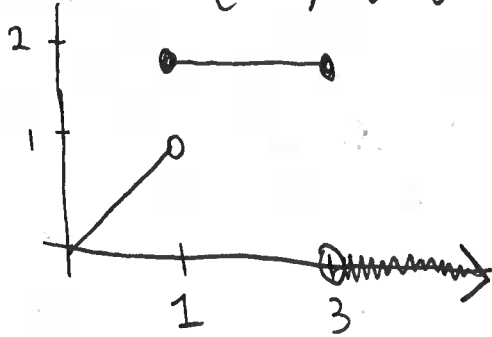
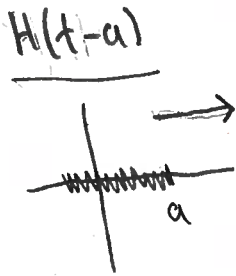


Ex 3.18

$$f(t) = \begin{cases} t, & 0 < t < 1 \\ 2, & 1 \leq t \leq 3 \\ 0, & t > 3 \end{cases}$$



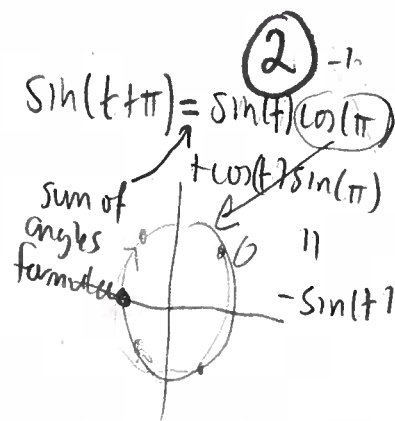
$$= t + \underbrace{(2-t)H(t-1)}_{\substack{\text{on} \\ \downarrow \\ \text{off} \\ \downarrow}} - 2H(t-3) \quad (1)$$



$$\begin{aligned} \mathcal{L}\{f(t)\} &= \mathcal{L}\{t\} + \mathcal{L}\{2H(t-1)\} - \mathcal{L}\{tH(t-1)\} - \mathcal{L}\{2H(t-3)\} \\ &= \frac{1}{s^2} + \frac{2}{s}e^{-s} - e^{-s}\mathcal{L}\{t+1\} - 2\frac{e^{-3s}}{s} \\ &= \frac{1}{s^2} + \frac{2}{s}e^{-s} - e^{-s}\left(\frac{1}{s^2} + \frac{1}{s}\right) - 2\frac{e^{-3s}}{s} \\ &= \frac{1}{s^2} + \frac{1}{s}e^{-s} - \frac{1}{s^2}e^{-s} - \frac{2}{s}e^{-3s} \end{aligned}$$

# Ex 3.19 Solve

$$\begin{cases} x'' + 4x = \sin(t) - H(t-\pi)\sin(t) \\ x(0) = 0, x'(0) = 0 \end{cases}$$



$$\begin{aligned} (\Delta^2 X(\Delta) - (x(0) - 0) - 0) + 4X(\Delta) &= \frac{1}{\Delta^2+1} - e^{-\pi\Delta} \mathcal{L}\{\sin(t+\pi)\} \\ &= \frac{1}{\Delta^2+1} + e^{-\pi\Delta} \frac{1}{\Delta^2+1} \end{aligned}$$

$$\Delta^2 X(\Delta) + 4X(\Delta) = \left(\frac{1}{\Delta^2+1}\right)(1+e^{-\pi\Delta})$$

$$X(\Delta) = \frac{1}{(\Delta^2+4)(\Delta^2+1)} + \frac{1}{(\Delta^2+4)(\Delta^2+1)} e^{-\pi\Delta}$$

$$\frac{1}{(\Delta^2+4)(\Delta^2+1)} = \frac{A\Delta+B}{\Delta^2+4} + \frac{C\Delta+D}{\Delta^2+1}$$

$$0\Delta^3 + 0\Delta^2 + 0\Delta + 1 = (A\Delta+B)(\Delta^2+1) + (C\Delta+D)(\Delta^2+4)$$

$$= A\Delta^3 + A\Delta + B\Delta^2 + B + C\Delta^3 + 4C\Delta + D\Delta^2 + 4D$$

$$= (A+C)\Delta^3 + (B+D)\Delta^2 + (A+4C)\Delta + (B+4D)$$

$$\begin{cases} A+C = 0 \rightarrow A = -C \\ B+D = 0 \rightarrow B = -D \\ A+4C = 0 \rightarrow 3C = 0 \rightarrow C = 0 \\ B+4D = 1 \rightarrow 3D = 1 \rightarrow D = \frac{1}{3} \rightarrow B = -\frac{1}{3} \end{cases}$$

So,  $\mathcal{L}^{-1}\left\{\frac{1}{\Delta^2+k^2}\right\} = \frac{1}{k} \sin(kt)$

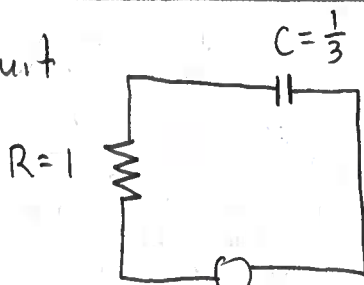
(3)

$$X(s) = \left[ \frac{-\frac{1}{3}}{\Delta^2+4} + \frac{\frac{1}{3}}{\Delta^2+1} \right] + \left[ \frac{-\frac{1}{3}}{\Delta^2+4} + \frac{\frac{1}{3}}{\Delta^2+1} \right] e^{-\pi\Delta}$$

$\downarrow \mathcal{L}^{-1}$   
 $4=2^2$        $1=1^2$

$$x(t) = \underbrace{\left[ -\frac{1}{6} \sin(2t) + \frac{1}{3} \sin(t) \right]}_{f(t)} + H(t-\pi) \left[ -\frac{1}{6} \sin(2(t-\pi)) + \frac{1}{3} \sin(t-\pi) \right]$$

Ex 3.21 RC circuit



$$\Rightarrow \begin{cases} q' + 3q = H(t-1) - H(t-2) \\ q(0) = 0 \end{cases}$$

$\mathcal{L} \downarrow$

$$(\Delta Q(\Delta) - 0) + 3Q(\Delta) = \frac{1}{\Delta} e^{-\Delta} - \frac{1}{\Delta} e^{-2\Delta}$$

$$Q(\Delta) = \frac{1}{\Delta(\Delta+3)} e^{-\Delta} - \frac{1}{\Delta(\Delta+3)} e^{-2\Delta}$$

$$q(t) = \mathcal{L}^{-1}\{Q\} = H(t-1) \frac{1}{3} (1 - e^{-3(t-1)}) - H(t-2) \frac{1}{3} (1 - e^{-3(t-2)})$$

$$\mathcal{L}^{-1}\left\{\frac{1}{\Delta(\Delta+3)}\right\} = \frac{1}{0-(-3)} (e^{0t} - e^{-3t}) = \frac{1}{3} (1 - e^{-3t})$$