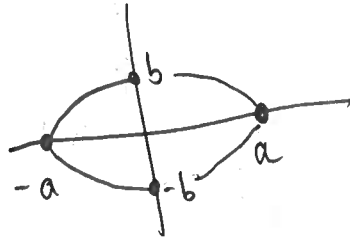


①

Ex: Find area of ellipse

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$



Parametrize ellipse:

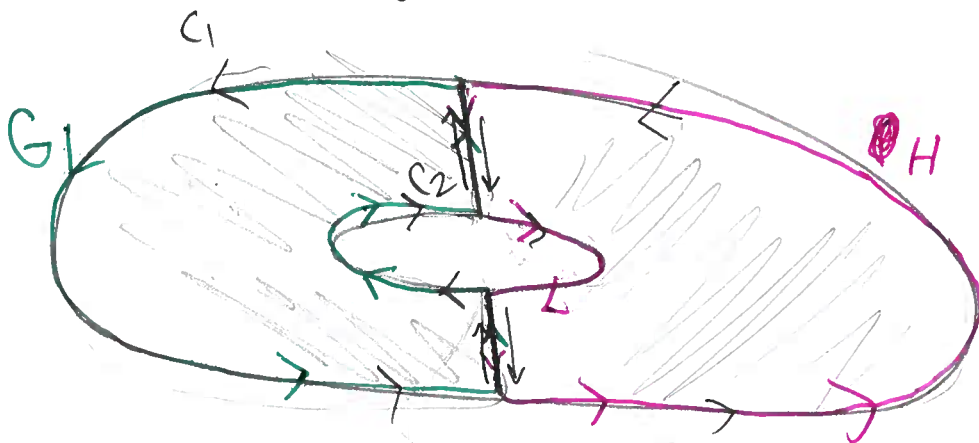
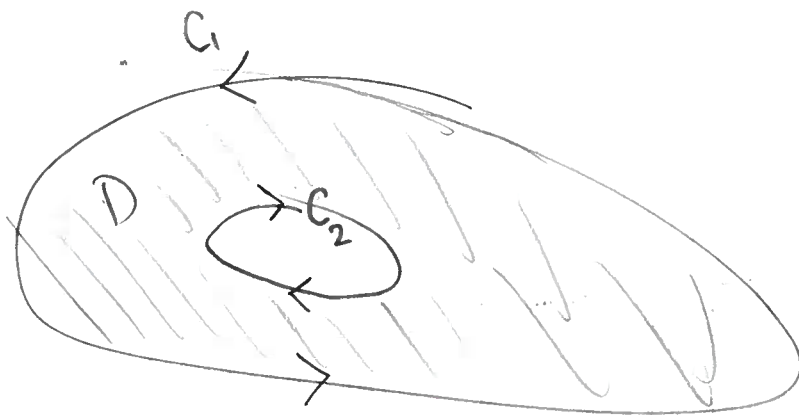
$$\begin{cases} \vec{r}(t) = \langle a \cos t, b \sin t \rangle \\ 0 \leq t \leq 2\pi \end{cases}$$

From earlier (last class)

$$\begin{aligned} \text{Area} &= \frac{1}{2} \int_{2\pi}^0 x dy - y dx \\ &= \frac{1}{2} \int_0^{2\pi} a \cos(t) b \sin(t) - b \sin(t) (-a \sin(t)) dt \\ &= \frac{1}{2} \int_0^{2\pi} ab (\underbrace{\cos^2(t) + \sin^2(t)}_{=1}) dt \\ &= \frac{1}{2} ab \int_0^{2\pi} 1 dt = \frac{2\pi ab}{2} = \pi ab \end{aligned}$$

2

What happens if our region is no longer simply connected?



$$\int_{C_1 \cup C_2} \equiv \int_{G \cup H}$$

So,

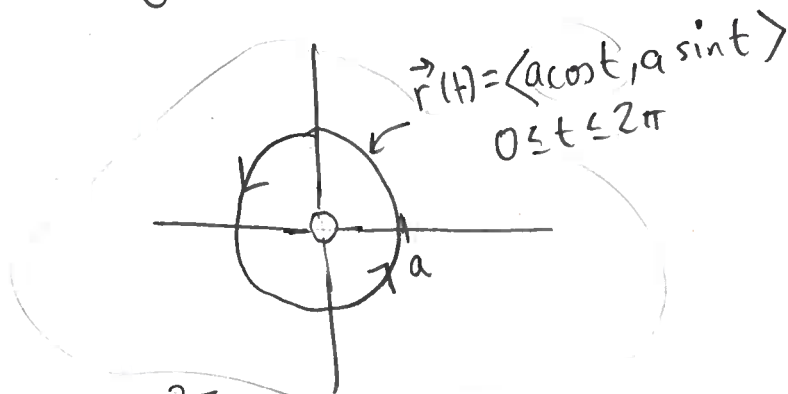
3

$$\iint_D \frac{\partial q}{\partial x} - \frac{\partial p}{\partial y} dA = \overbrace{\int_{C_1 \cup C_2} p dx + q dy}^{\text{strange}} = \int_G p dx + q dy + \int_H p dx + q dy$$

Ex: $\vec{F} = \left\langle \frac{-y}{x^2+y^2}, \frac{x}{x^2+y^2} \right\rangle$

This vector field is not defined at $(x,y) = (0,0)$.

Compute $\int_C \vec{F} \cdot d\vec{r}$ where C is circle w/ radius a .



$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_0^{2\pi} \left\langle \frac{-a \sin t}{a^2 \cos^2(t) + a^2 \sin^2(t)}, \frac{a \cos t}{a^2 \cos^2(t) + a^2 \sin^2(t)} \right\rangle \cdot \langle -a \sin t, a \cos t \rangle dt \\ &= \int_0^{2\pi} \frac{a^2 \sin^2(t)}{a^2} + \frac{a^2 \cos^2(t)}{a^2} dt \\ &= \int_0^{2\pi} 1 dt = 2\pi \end{aligned}$$

Curl and divergence of vector fields

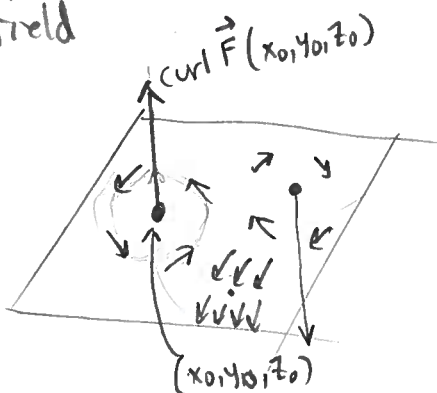
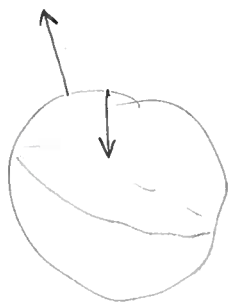
4

Recall: $\nabla f = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right\rangle$

implies we should think of ∇f as

$\vec{\nabla} f$ where $\vec{\nabla} = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle$

Curl - measures rotation around points of a vector field



Turns out:

$$\text{Curl } \vec{F} \stackrel{\text{def}}{=} \nabla \times \vec{F} \leftarrow \vec{F} = \langle P, Q, R \rangle$$

$$= \det \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{bmatrix}$$

Some thing from Green's theorem

$$= \left\langle \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}, -\left(\frac{\partial R}{\partial x} - \frac{\partial P}{\partial z}\right), \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right\rangle$$

(5)

Ex: $\vec{F} = \langle xz, xyz, -y^2 \rangle$

$$\text{curl } \vec{F} = \nabla \times \vec{F}$$

$$= \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xz & xyz & -y^2 \end{bmatrix}$$

$$= \langle -2y - xy, -(-x), yz \rangle$$

$$= \langle -2y - xy, x, yz \rangle$$

Theorem: $\text{curl}(\nabla f) = \vec{0}$ (provided f has continuous partial derivatives)

Proof: $P = \frac{\partial f}{\partial x}$, $Q = \frac{\partial f}{\partial y}$, $R = \frac{\partial f}{\partial z}$

Directly,

$$\text{curl } \nabla f = \left\langle \underbrace{f_{zy} - f_{yz}}_{=0 \text{ if } f \text{ is nice}}, \underbrace{-(f_{zx} - f_{xz})}_{=0}, \underbrace{f_{yx} - f_{xy}}_{=0} \right\rangle$$

$$= \langle 0, 0, 0 \rangle$$

significance: if $\text{curl } \vec{F} \neq \vec{0}$, then \vec{F} is not conservative