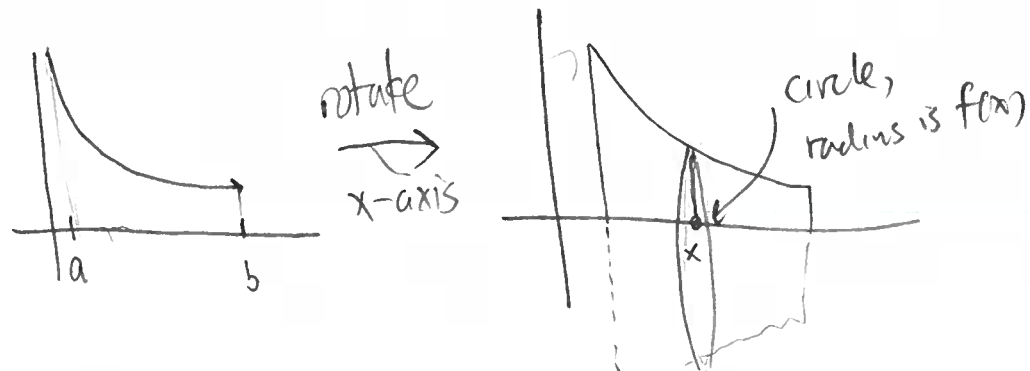


# Surfaces of revolution

1

Recall: rotate  $f(x)$  about an axis



Parametrize:

$$\vec{r}(x, \theta) = \langle x, f(x)\cos(\theta), f(x)\sin(\theta) \rangle$$

$$0 \leq \theta \leq 2\pi$$

$$a \leq x \leq b$$

Ex: Rotate  $f(x) = 1 - x^2$  about  $x$ -axis  
 $0 \leq x \leq 1$

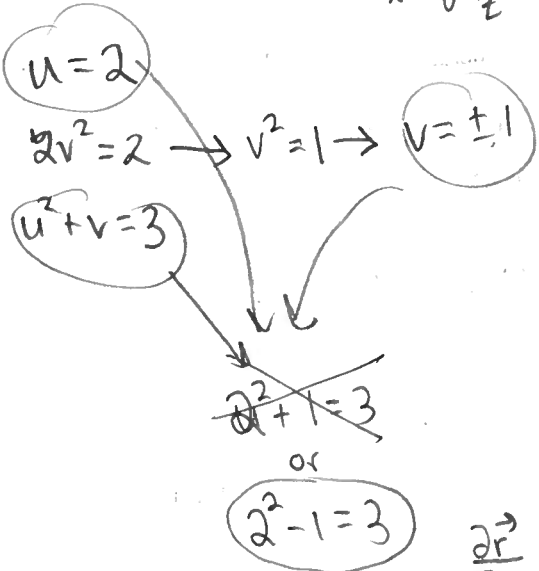
$$\begin{cases} \vec{r}(x, \theta) = \langle x, (1-x^2)\cos(\theta), (1-x^2)\sin(\theta) \rangle \\ 0 \leq x \leq 1 \\ 0 \leq \theta \leq 2\pi \end{cases}$$

EX: Find eqn of tangent plane of surface

$$\vec{r}(u,v) = \langle u, 2v^2, u^2+v \rangle$$

at (2,2,3)

Which  $u,v$  give us  $(2,2,3)$ ?



$\Rightarrow u=2, v=-1$

Recall

- tan plane requires
- ① pt plane ✓
- ② vector  $\perp$  to plane

Vector  $\perp$  to plane:  $\vec{n} = \vec{r}_u \times \vec{r}_v$

$u=1, v=1$   
 $\vec{r}(1,1) = \langle 1, 2, 2 \rangle$   
 $\vec{r}_u = \langle 1, 0, 2 \rangle$   
 $\vec{r}_v = \langle 0, 4, 1 \rangle$   
 $\vec{r}_u \times \vec{r}_v = \langle -8, -1, 4 \rangle$

at  $u=2, v=-1$   
 $\vec{r}_u = \langle 1, 0, 4 \rangle$   
 $\vec{r}_v = \langle 0, -4, 1 \rangle$   
 $\vec{r}_u \times \vec{r}_v = \langle 16, -1, -4 \rangle$

↓ Tan plane

$$16(x-2) - (y-2) - 4(z-3) = 0$$

$$\begin{aligned}
 &= \langle 1, 0, 2u \rangle \times \langle 0, 4v, 1 \rangle \\
 &= \det \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & 2u \\ 0 & 4v & 1 \end{bmatrix} \\
 &= \langle -8uv, -(1-0), 4v \rangle \\
 &= \langle -8uv, -1, 4v \rangle
 \end{aligned}$$

Surface area:

parametric surface  $\begin{cases} \vec{r}(u,v) \\ u,v \in D \end{cases}$

$$\delta A = \iint_D \|\vec{r}_u \times \vec{r}_v\| dA$$

Ex: Find surface area of a sphere of radius  $a$ .

Soln: Parametrize using spherical coordinates

$$\begin{cases} \vec{r}(\theta, \phi) = \langle a \sin(\phi) \cos(\theta), a \sin(\phi) \sin(\theta), a \cos(\phi) \rangle \\ 0 \leq \theta \leq 2\pi \\ 0 \leq \phi \leq \pi \end{cases} D: \begin{array}{c} \phi \\ \begin{array}{|c|} \hline \text{rectangle} \\ \hline \end{array} \\ \theta \end{array}$$

So,

$$\text{Surface Area} = \iint_D \|\vec{r}_\theta \times \vec{r}_\phi\| dA$$

*there must be an error here somewhere*

$$\vec{r}_\theta \times \vec{r}_\phi = \langle a \sin(\phi)(-s(\theta)), a \sin(\phi)c(\theta), 0 \rangle \times \langle a c(\phi)c(\theta), a c(\phi)s(\theta), -a c(\phi) \rangle$$

$$= \det \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ -a \sin(\phi) s(\theta) & a \sin(\phi) c(\theta) & 0 \\ a c(\phi) c(\theta) & a c(\phi) s(\theta) & -a c(\phi) \end{bmatrix} = -a^2 \sin(\phi) c(\phi) [s^2(\theta) + c^2(\theta)]$$

$$= \langle -a^2 \sin(\phi) c(\theta) c(\phi), -(a^2 \sin(\phi) s(\theta) c(\phi) - 0), -a^2 \sin(\phi) c(\phi) s^2(\theta) - a^2 \sin(\phi) c(\phi) c^2(\theta) \rangle$$

$$\begin{aligned} \|\vec{r}_{\theta} \times \vec{r}_{\phi}\| &= \sqrt{a^4 \underbrace{s^2(\phi) c^2(\theta) c^2(\phi)} + a^4 \underbrace{s^2(\phi) s^2(\theta) c^2(\phi)} + a^4 \underbrace{s^2(\phi) c^2(\phi)}} \\ &= \sqrt{a^4 \underbrace{s^2(\phi) c^2(\phi)} (\underbrace{c^2(\theta) + s^2(\theta)}_{=1}) + a^4 s^2(\phi) c^2(\phi)} \end{aligned}$$