

Discrete special functions

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Difference calculus

Forward difference:

$$\Delta f(t) = f(t + 1) - f(t)$$

Backward difference:

$$\nabla f(t) = f(t) - f(t - 1)$$

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	Continuous	Discrete
Sum Rule	$(f + g)' = f' + g'$	$\Delta(f + g) = \Delta f + \Delta g$
Product Rule	$(fg)' = f'g + g'f$	$\Delta(fg) = g\Delta f + f^\sigma \Delta g$
Quotient Rule	$\left(\frac{f}{g}\right)' = \frac{gf' - fg'}{g^2}$	$\Delta\left(\frac{f}{g}\right) = \frac{g\Delta f - f\Delta g}{gg^\sigma}$

Discrete polynomials

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$$(a)_k = a(a+1)(a+2)\dots(a+k-1).$$

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(proof left to audience)

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A discrete power rule!

Also:

$$t(-1)^n \underbrace{(-(t-1))_n}_{\text{shifted in } t} = (-1)^{n+1}(-t)_{n+1}$$

Classical hypergeometric series

For $p, q \in \{0, 1, 2, \dots\}$:

$${}_pF_q(a_1, \dots, a_p; b_1, \dots, b_q; t) = \sum_{k=0}^{\infty} \frac{(a_1)_k \dots (a_p)_k t^k}{(b_1)_k \dots (b_q)_k k!}$$

Classical hypergeometric series

	Function	${}_p\mathcal{F}_q$ representation
Exponential	$e^{\alpha t}$	${}_0\mathcal{F}_0(;; \alpha t)$
Cosine	$\cos(at)$	${}_0\mathcal{F}_1\left(\left;; \frac{1}{2}; -\frac{(at)^2}{4}\right)$
Sine	$\sin(at)$	$at {}_0\mathcal{F}_1\left(\left;; \frac{3}{2}; -\frac{(at)^2}{4}\right)$
Bessel	$J_n(t)$	$\frac{z^n}{2^n \Gamma(n+1)} {}_0\mathcal{F}_1\left(\left;; n+1; -\frac{t^2}{4}\right)$
Polylogarithm	$\text{Li}_m(t)$	$t {}_{m+1}\mathcal{F}_m(1, 1, \dots, 1; 2, 2, \dots, 2; t)$
Sine integral	$\text{Si}(t)$	$t {}_1\mathcal{F}_2\left(\frac{1}{2}; \frac{3}{2}, \frac{3}{2}; \frac{t^2}{4}\right)$
Assoc. Laguerre poly	$L_n^{(\alpha)}(t)$	$\frac{(\alpha+1)_n}{n!} {}_1\mathcal{F}_1(-n; \alpha+1; t)$
\vdots	\vdots	\vdots

Fundamental trick:

replace t^m with $(-1)^m (-t)_m$

and

replace $tf(t)$ with $t \underbrace{f(t-1)}_{\text{shifted in } t}$

Next to equations with constant coefficients, which we studied in § 4, Chap. I, the simplest linear homogeneous difference equations of higher than the first order are those with linear coefficients. The second order equation of this type, namely

$$(99) \quad (a_2 x + b_2) y(x + 2) + (a_1 x + b_1) y(x + 1) \\ + (a_0 x + b_0) y(x) = 0,$$

is called the *hypergeometric difference equation*, because, as we shall see in § 7, its solutions can be expressed in terms of the hypergeometric series

$$(100) \quad F(\alpha, \beta, \gamma, z) = 1 + \frac{\alpha\beta}{1 \cdot \gamma} z + \frac{\alpha(\alpha + 1)\beta(\beta + 1)}{1 \cdot 2 \gamma(\gamma + 1)} z^2 + \dots$$

Discrete hypergeometric series – prior notions

Batchelder (1916): “hypergeometric difference equation”

$$(a_2x + b_2)y(x + 2) + (a_1x + b_1)y(x + 1) + (a_0x + b_0)y(x) = 0.$$

Difference equations of hypergeometric type:

$$\sigma(t)\Delta\nabla y(t) + \tau(t)\Delta y(t) + \lambda y(t) = 0.$$

Khan (1994): “discrete hypergeometric function” (a q -analogue)

$${}_rM_s(a_1, \dots, a_r; b_1, \dots, b_s; q, z) = \sum_{k=0}^{\infty} \frac{(q^{a_1})_k \dots (q^{a_r})_k z^{(k)}}{(q)_k (q^{b_1})_k \dots (q^{b_s})_k}.$$

Discrete hypergeometric series

$${}_pF_q(a_1, \dots, a_p; b_1, \dots, b_q; t, n, \xi) = \sum_{k=0}^{\infty} \frac{(a_1)_k \cdots (a_p)_k}{(b_1)_k \cdots (b_q)_k} \frac{\xi^k (-1)^{nk} (-t)_{nk}}{k!}$$

Discrete hypergeometric series

$${}_pF_q(a_1, \dots, a_p; b_1, \dots, b_q; t, n, \xi) = \sum_{k=0}^{\infty} \frac{(a_1)_k \cdots (a_p)_k \xi^k (-1)^{nk} (-t)_{nk}}{(b_1)_k \cdots (b_q)_k k!}$$

Relationship between ${}_pF_q$ and ${}_p\mathcal{F}_q$:

$$\begin{aligned} & {}_pF_q(a_1, \dots, a_p; b_1, \dots, b_q; t, n, \xi) \\ &= {}_{p+n}\mathcal{F}_q\left(a_1, \dots, a_p, \frac{-t}{n}, \frac{-t+1}{n}, \dots, \frac{-t+n-1}{n}; b_1, \dots, b_q; (-n\xi)^n\right) \end{aligned}$$

Convergence

Let $y(t) = {}_pF_q(a_1, \dots, a_p; b_1, \dots, b_q; t)$.

Theorem: $y(t)$ **always** converges for all $t \in \mathbb{N}$. If $t \in \mathbb{C} \setminus \mathbb{N}$ and $\xi \in \mathbb{C}$, then $y(t)$ converges whenever $p + n < q + 1$ or both $p + n = q + 1$ and $|\xi|n^n < 1$. If $p + n > q + 1$ or both $p + n = q + 1$ and $|\xi|n^n > 1$, then $y(t)$ diverges. If $p + n = q + 1$ and $|\xi|n^n = 1$, then $y(t)$ converges

provided that $\operatorname{Re} \left(\sum_{k=1}^q b_k - \sum_{k=1}^p a_k - \frac{1}{n} \sum_{k=0}^{n-1} -t + k \right) > 0$.

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Proof: Routine application of ratio test plus citing a well-known theorem about ${}_pF_q$.

New special functions

Classic Function	Discrete ${}_pF_q$ -analogue
$e^{\alpha t}$	${}_0F_0(;; t, 1, \alpha)$
$\cos(at)$	${}_0F_1\left(\left;; \frac{1}{2}; t, 2, -\frac{a^2}{4}\right)$
$\sin(at)$	$at {}_0F_1\left(\left;; \frac{3}{2}; \underbrace{t-1}_{\text{shift}}, 2, -\frac{a^2}{4}\right)$
$J_n(t)$	$\frac{(-1)^n (-t)_n}{2^n \Gamma(n+1)} {}_0F_1\left(\left;; n+1; t-n, 2, -\frac{1}{4}\right)$
$\text{Li}_m(t, n, 1)$	$t_{m+1} F_m(1, 1, \dots, 1; 2, 2, \dots, 2; t-1, n, 1)$
$\text{Si}(t)$	$t {}_1F_2\left(\left(\frac{1}{2}; \frac{3}{2}, \frac{3}{2}; \underbrace{t-1}_{\text{shift}}, 2, 4\right)\right)$
$L_n^{(\alpha)}(t)$	$\frac{(\alpha+1)_n}{n!} {}_1F_1(-n; \alpha+1; t, 1, 1)$
\vdots	\vdots

New special functions

What properties are preserved? What properties disappear?

Exponential

Classic: ${}_0\mathcal{F}_0(;;; \alpha t) = e^{\alpha t}$

Discrete: ${}_0F_0(;;; t, 1, \alpha) = (1 + \alpha)^t$

Classic Property	Discrete Property
Solves $y' = y, y(0) = 1$	Solves $\Delta y(t) = y(t), y(0) = 1$
Positive everywhere	Positive everywhere iff $1 + \alpha > 0$
Laplace transform: $\frac{1}{z - \alpha}$	\mathbb{Z} -Laplace transform $\frac{1}{z - \alpha}$

New special functions

Cosine

Classic: $\cos(\alpha t) = {}_0\mathcal{F}_1\left(\left(; \frac{1}{2}; -\frac{\alpha^2 t^2}{4}\right)\right)$

Discrete: $\cos_\alpha(t) = {}_0F_1\left(\left(; \frac{1}{2}; t, 2, -\frac{\alpha^2}{4}\right)\right)$

Classic Property	Discrete Property
Solves $y'' = -y$, $\begin{cases} y(0) = 1 \\ y'(0) = 0 \end{cases}$	Solves $\Delta^2 y(t) = y(t)$, $\begin{cases} y(0) = 1 \\ \Delta y(0) = 0 \end{cases}$
Bounded in $[-1, 1]$	Unbounded
Oscillatory	Oscillatory
Laplace transform: $\frac{1}{z - \alpha}$	\mathbb{Z} -Laplace transform $\frac{1}{z - \alpha}$

New special functions

Sine

Classic: $\sin(\alpha t) = \alpha t {}_0F_1 \left(; \frac{3}{2}; -\frac{\alpha^2 t^2}{4} \right)$

Discrete: $\sin_\alpha(t) = \alpha t {}_0F_1 \left(; \frac{3}{2}; \underbrace{t-1, 2}_{\text{shift}}, -\frac{\alpha^2}{4} \right)$

Classic Property	Discrete Property
Solves $y'' = -y$, $\begin{cases} y(0) = 1 \\ y'(0) = 0 \end{cases}$	Solves $\Delta^2 y(t) = y(t)$, $\begin{cases} y(0) = 0 \\ \Delta y(0) = 1 \end{cases}$
Bounded in $[-1, 1]$	Unbounded
Oscillatory	Oscillatory
Laplace transform: $\frac{1}{z - \alpha}$	\mathbb{Z} -Laplace transform $\frac{1}{z - \alpha}$
$\cos^2(\alpha t) + \sin^2(\alpha t) = 1$	$\cos_\alpha^2(t) + \sin_\alpha^2(t) = e_{\alpha^2}(t)$

New special functions

Bessel

Classic: $\mathcal{J}_n(t) = \frac{t^n}{2^n \Gamma(n+1)} {}_0\mathcal{F}_1 \left(; n+1; -\frac{t^2}{4} \right)$

Discrete: $\mathcal{J}_n(t) = \frac{(-1)^n (-t)_n}{2^n \Gamma(n+1)} {}_0\mathcal{F}_1 \left(; n+1; \underbrace{t-n}_{\text{shift}}, 2, -\frac{1}{4} \right)$

Classic Property	Discrete Property
$t^2 y'' + ty' + (t^2 - n^2)y = 0$	$(-t)_2 \Delta^2 y(t-2) + t \Delta y(t-1) + (-t)_2 y(t-2) - n^2 y(t) = 0$
Oscillatory	Oscillatory
Bounded, decays to zero	Unbounded
\mathcal{L} Transform: $\frac{[\sqrt{z^2+1}+z]^{-n}}{\sqrt{z^2+1}}$	\mathbb{Z} -Laplace Transform: $\frac{[\sqrt{z^2+1}+z]^{-n}}{\sqrt{z^2+1}}$

New special functions

Dilogarithm

Classic: $\mathcal{L}i_2(t) = - \int_0^t \frac{\ln(1-\tau)}{\tau} d\tau = {}_3F_2(1, 1, 1; 2, 2; t) = \sum_{k=1}^{\infty} \frac{t^k}{k^2}$

Discrete: $\text{Li}_2(t, n, \xi) = {}_3F_2(1, 1, 1; 2, 2; \underbrace{t-1}_{\text{shift}}, n, \xi)$

Classic Property	Discrete Property
$(1-t)ty'' + (1-t)y' = 1$	$t\Delta^2 y(t-1) - (-t)_2 \Delta^2 y(t-2) + \Delta y(t) - t\Delta y(t-1) = 1$
$\mathcal{L}i_2(t) + \mathcal{L}i_2(-t) = \frac{1}{2}\mathcal{L}i_2(t^2)$	$\text{Li}_2(t, 1, 1) + \text{Li}_2(t, 1, -1) = \frac{1}{2}\text{Li}_2(t, 2, 1)$
$\text{Li}_2(1-z) + \text{Li}_2\left(1-\frac{1}{z}\right) = -\frac{\ln^2(z)}{2}$???
$\text{Li}_2(2) = \frac{\pi^2}{4} - i\pi \ln(2)$???

Open questions galore

1. Pick your favorite special function.
2. Find its hypergeometric representation (e.g. in a reference like Abramowitz and Stegun).
3. Carry over parameters and coefficients, keeping in mind the “fundamental trick”.
4. Explore!

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Thanks

Thanks for your attention!

<http://tomcuchta.com> (slides will be posted)